1. IMCA Telemetry Device

	Revision History						
Revision	Date	Author	Comments				
1	November 9, 2011	G Wright	Initial draft				
1	March 26, 2012	G Wright	Add C-O feature				
1	October 12, 2012	G. Wright	Documented C-O for Elevation				
1.1	May 11, 2015	G. Wright	Updated figure and refined				
			description of shift options				
1.2	August 24, 2020	G. Wright	Added Stale Data option				
2.0	February 6, 2024	S. Westaway	Device Updated				
2.1	June 09, 2025	S. Westaway	Anchor Spread Message Added				

1.1 Overview

The IMCA Telemetry device supports the IMCA Telemetry standard as defined by the IMCA document, *Inter-Vessel Survey Data Standard Telemetry Protocol IMCA S 006 Rev. 1, April 2003.*

1.2 Data Types

The device supports the following data types:

- P Positioning
 - Geographic 2D position
 - Height (published as an Elevation observation)
 - standard deviation (latitude and longitude standard deviations)
 - position source
 - position status
- K Stationing
 - Line name
 - KP
 - Distance cross course
- H Heading (True)
- R Attitude
 - Pitch
 - Roll
- D Bathy
 - Water depth
 - Altitude
- B Burial
 - Depth of Burial
- A Acoustic (Receive Only)
 - Beacon ID or Address
 - Number of ranges (LBL Acoustics)

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- Standard deviation
- RMS
- T Tow
 - Tension
- M Message
 - ASCII Message
- A Auxiliary
 - Data not previously defined as above
- ANC Anchor Spread (Transmit Only)
 - Active anchor spread
 - Proposed anchor spread

1.3 Message Validation

The messages are NMEA-like and as such are checked for only NMEA valid characters as the first step of data validation. If any non-compliance is detected, the message is not processed further.

All messages by definition include a NMEA-like checksum. If the checksum is present, it is checked, and the message is only processed further if it passes. If the checksum is not present, the message processing continues as if one was present, and it passed.

1.4 Units

All distances in message are output in metres and all angles in message are output in degrees regardless of local units. Local units are applied within receiving package. Time in message is UTC.

1.5 Identifiers

The message is identified by the IDs field. This field is used by NavView to identify and associate the respective data as sources for Calculations.



Figure 1 ID Field - Position and Heading Identifier

1.6 Output

The implementation of this device does not support output of the general messages.

1.7 Observations

The IMCA device supports the following observation types as obtained from the respective message type. Note that all will appear for selection in the respective dialogs, even if not available.



- Geographics2D Position: Positioning message (P) Body State
- Heading:
 - Heading message (H) Body State Pitch/Roll: Attitude (R) - Body State
- Route Guidance: Stationing (K) – Line Name, KP, DCC
- Positioning (P) Body State Elevation:
- Force:

Altitude/Depth:

- Tension (T) Bathy (D)
- Burial: Burial (B)

1.8 Operation

The IMCA Telemetry device supports inputs from multiple sources, i.e. vessels. These sources are determined from the description field in the message. NavView maintains a list of the vessels for which messages are received. When a message is received, once it passes validation, the description field is checked and if the source is not already on the list, it is added. The message is then decoded and the observations for the data present are published. Note that sources are not automatically removed from the list under any circumstances.

- **Note:** Message descriptions containing only numbers and/or decimal places are acceptable and used if manually entered as part of the configuration but are not automatically added due to the potential for them resulting from a misaligned time field.
- Note: Station needs to be set to Active to enable broadcast of device message.



Figure 2 Project Configuration _ Active Station Setting

1.9 Add Device

- 1. Select Devices from the Configuration section of the Setup ribbon to open the IO Devices window.
- 2. Select Configurable Output in the drop-down list.

IO Devices		
IMCA Telemetry	€ ● ★ ₹ 🐒	E 📔 🗰 📀
Туре	Name	I/O Config

Figure 3 IO Devices Window

3. Click the add 🖸 button, this will open the Configure Device I/O dialog.



Q Cor	nfigure Devi	ce I/O	_) X
Name:	IMCA Telen	netry			
	Telemetry -				
0	Serial				
0	UDP Client				
0	TCP Client				
0	TCP Server				
0	File				
0	Client Web S	Socket			
Ser	ial ———				
Qı	iery status:				
Po	rt Name:	в сом	1 -		
Ba	ud Rate:	9600	•		
Da	ita Bits:	8	*		
Pa	rity:	None	•		
Sto	op Bits:	1	•		
		OK	Ca	ncel	Apply

Figure 4 Configure Device I/O

- 4. Configure I/O as required. Refer to *Device* section in the NavView User Guide for I/O configuration.
- 5. Click Okay.

1.10 Configure Device

1. Click the configure device 🔲 button to open Configure IMCA Telemetry dialog.

Configure IMCA Telem	etry	-				
Receive Transmit						
Options						
Use message time						
Latency	0.000 s]		
Input Geographic CRS	WGS 84 ge	ographic 2D	(4326) 👻			
Reject stale data						
Message Options —						
+	ŧ					
Descriptor Auxiliary Data						
Auto detect and add	messages					
		OK	Cancel			

Figure 5 Configure IMCA Telemetry

2. Select Receive Tab or Transmit Tab for configuration.

Note: Data can be transmitted and received on the same IMCA Telemetry device.



1.10.1 Transmit Tab Configuration

Configure IMCA Telemetry	_		\times
Receive Transmit			
Output Geographic CRS WGS 84 geographic 2D (4326) 💌]		
Descriptor			
	OK	Ca	ncel

Figure 6 Transmit Tab

1.10.1.1 General Settings

- Output Geographic CRS: Select the 2D Geographic CRS to be used in output message
- 1.10.1.2 Message Descriptions

The message Descriptor is used to identify what the data is referred to, i.e. Vessel CRP.

1. Click the Add button to add a row to the data grid to allow entry of a new description.



Figure 7 Message Description Dialog

2. Multiple **Descriptors** can be added to the device. Check the **Enabled** box to activate the Selected Report.



- 3. In the **Descriptor** field enter a description that will be added to the message that will be used to identify the selected report.
- 4. Select what data will be added to the message.
 - Body State: From the drop-down menu select the vehicle data to output
 - **Output:** Position: Heading, Elevation and Attitude (Pitch and Roll)

Note: Max age is used to reject stale data based on the value entered.

- Route Guidance: From the drop-down menu select a route guidance that has been created in Guidance Calculations
 - **Output**: Station (KP), Line Name and DCC(m)
- Bathymetry Elevation: Options available are Contant or Observation
 - **Output**: Elevation(m)
- Bathymetry Altitude: Options available are Constant or Observation
 - **Output**: Distance(m)
- Burial: Options available are Constant or Observation
 - **Output:** Burial Depth(m)
- Tension: Options available are Constant or Observation
 - **Output:** Force(kN)
- Anchor Spread: Options available are Active anchor spread or Proposed anchor spread. Only one option can be selected
 - Output: Active or Proposed anchor spread

Configure IMCA Telemetry	/		—					
Receive Transmit								
Output Geographic CRS	Output Geographic CRS WGS 84 geographic 2D (4326)							
❹ № 0 ♠ ₹	Selected Report							
Descriptor	Enabled 🗹 Transmit Ir	nterval (hh:mm:ss) 00:00:05						
FPUCRP	Descriptor	FPUCRP						
Route Guidance	Body state	Vehicles/FPU/Offsets/CRP *	Max age	30 s				
BathyElevation	Route guidance	None						
BathyAltitude	Bathymetry elevation	None *						
TowTension	Bathymetry altitude	None 💌						
AnchorActive	Durial							
	Burlai	None						
	lension	None 🛛 👻						
	Active anchor spread	None		~				
	Proposed anchor spread	None		~				
			01/					
			OK	Cancel				

Figure 8 IMCA Telemetry Transmit Configuration Example



Time	Data	
02-Feb-2024 10:37:07	\$4DTEL,PHR,VesselCRP,143707.873,27.9697095,-91.4628834,30.480,0.000,0,0,105.32,10.00,0.00*37	
02-Feb-2024 10:37:06	\$4DTEL,PHR,VesselCRP,143706.876,27.9697107,-91.4628884,30.480,0.000,0,0,105.32,10.00,0.00*32	

Figure 9 IMCA Telemetry Transmit Message Example

1.10.2 Receive Tab Configuration

Configure IMCA Teleme	Configure IMCA Telemetry - C X						
Receive Transmit							
Options							
Use message time							
Latency	0.000 s						
Input Geographic CRS	WGS 84 geographic 2D (4326)						
Reject stale data							
Message Options							
+							
Descriptor	Auxiliary Data			—			
Auto detect and add messages							
		ОК	Ca	ancel			

Figure 10 Receive Tab

- 1.10.2.1 General Settings
 - Use Message Time: Check this box to use the UTC time in the message as the data timestamp. Leave this box unchecked if the message is to use the NavView system time as the data timestamp
 - Latency: If the Use message time box is unchecked, a known latency can be entered to be applied to the system time the message is received for the data time stamp
 - Input Geographic CRS: Select the 2D Geographic CRS in the message
 - **Reject Stale Data:** Check the box to reject data that does not change,

1.10.2.2 Message Options

- 1. Click the Add button to add a row to the data grid to allow entry of a new **Descriptor**, see Figure 11.
- 2. Enter the Descriptor to be detected and decoded. The entry must be exactly the same as it appears in the message.
- **Note:** If **Auto detect and add messages** is selected, the device will read the Descriptor in the incoming message then add it to the list for use.



3. The decoded data can be used in Calculations, see Figure 12.

Configure IMCA Telemetry	-		\times
Receive Transmit			
Options			
Use message time			
Input Geographic CRS WGS 84 geographic 2D (4326)			
Reject stale data			
Message Options			
Descriptor Auxiliary Data			
VesselCRP Inputs Observation Mapping			_
		€	
Name Data Type Units			
Auto detect and add messages			
	ок	Ca	ncel

Figure 11 Descriptor Added



Figure 12 IMCA Device Data Available

1.10.2.3 Auxiliary Data

Auxiliary Data is used to decode data contained in the IMCA message that is not a previously defined data type.

Use of this would depend on the users at both ends knowing what was being passed and in what order.

As an example an IMCA message received contains **Tow** Tension data which is a previously defined data type and also contains auxiliary data from a cable counter CC1 which is not a previously defined data type.

Note: Refer to document *Inter-Vessel Survey Data Standard Telemetry Protocol IMCA S 006 Rev. 1, April 2003* for auxiliary message format, see Figure 13.



Time	Data
06-Feb-2024 14:37:35	\$FGTEL,TX,Tow,183735.891,8.93,1,626.666
06-Feb-2024 14:37:34	\$FGTEL,TX,Tow,183734.894,8.93,1,626.362
06-Feb-2024 14:37:33	\$FGTEL,TX,Tow,183733.894,8.93,1,626.058

Figure 13 IMCA Message Containing Auxiliary Data

To define the cable counter CC1 data type to be available as an observation;

1. Select the **Inputs** tab to define the CC1 data type.

Message Options ———				
€ 1 0 1 4				
Descriptor	Auxiliary D	lata		
Tow	Inputs	Observation N	lapping	
				•
	Name	Data Type	Units	

Figure 14 Auxiliary Data – Inputs Tab

2. Click the Add button to add a data type definition. In this example we want to define CC1.

Γ	Auxiliary Data							
	Inputs Observation Mapping							
					• •			
	Name	Data Type	Units					
	CC1	Distance		Metre				

Figure 15 CC1 Data Type

- 3. Enter Name for the data type definition
- 4. Select the data type, in this example it is Distance
- 5. Select the units as it is in the message string, this will be converted to local units
- **Note:** If the message string contains more than one auxiliary data, add the data types in the **Inputs** tab in the order they appear in the message string.
- 6. Select the **Observation Mapping** tab to configure the data type definition.



Figure 16 Observation Mapping Tab



7. From the drop-down menu select the item, in this example Distance is selected, then click the Add button to add to the list

Inputs	Observation Mapping	9				
					Dist	ance 💌 🕂 🖨
Name	Observation Type	Fields				
		Property	Field Type	Source	Source	Constant Value
CC1	DistanceObservation	Distance	Distance	Observation V	CC1 *	0.000 m
		SigmaDistance	Distance	Constant 🛛 👻	None	0.000 m

Figure 17 Auxiliary Data Type Configuration

- 8. Enter Name of the defined data as it will appear in Observations
- 9. Select if the data is from an Observation or a Constant from the drop-down menu
- 10. Select the Source from drop-down menu, this is taken from data type definitions added in the Inputs tab
- 11. The cable counter CC1 data will now be available, see Figure 18

Available Items		
▼ Observations		
Beacons		
Acoustics		
Connections		
► Calculations		
► Guidance		
IO Connections		
► Simulation		
Devices		
► 1 PPS		
Configurable Input		
► GPS 1		
► GPS 2		
► Gyro 1		
► Gyro 2		
▼ IMCA Telemetry In		
▼ IMCA		
▼ Tow		
Auxiliary Data	Text	→ Ţ
▼ CC1	Tow Tonsion	12 47 kN
Distance	TOW TENSION	12.47 KN
► Time	CC1	90.51 ftUS
σ Distance		
Rathy Altitude		

Figure 18 Auxiliary Data - CC1

1.10.3 Anchor Spread Message

Currently NavView only supports transmitting the IMCA Anchor Spread Message.

1.10.3.1 Transmit Tab Configuration

1. Click the Add button to add the anchor data to the data grid.



Sconfigure IMCA Telemetry	,		-		×
Receive Transmit					
Output Geographic CRS W	/GS 84 geographic 2D (4326) - Selected Peppert	•			
Descriptor	Enabled 🗹 Transmit Ir	iterval (hh:mm:ss) 0	0:00:01		
Active Anchors	Descriptor	Active Anchors			
	Body state	None 👻 Max ag	e 30 s		
	Route guidance				
	Bathymetry elevation				
	Bathymetry altitude				
	Burial				
	Tension				
	Active anchor spread	Vehicles/FPU/Ancho	rs/Anchor	Spread	-
	Proposed anchor spread	None			2
			ОК	Canc	el

Figure 19 Anchor Message Transmit Tab

- 2. Select **Active anchor spread** or **Proposed anchor spread** in Selected Report panel. Not able to select both for same **Descriptor**. If both Active and Proposed are to be transmitted create a separate Descriptor for each. See example below.
 - a. **Active anchor spread:** This outputs the active anchor spread from the selected vehicle containing the anchors

Configure IMCA Telemetry		- 🗆 X
Receive Transmit		
Output Geographic CRS	/GS 84 geographic 2D (4326)	•
	- Selected Report	terval (hh:mm:ss) 00:00:01
Descriptor Active Anchors	Descriptor	Active Anchors
Proposed Anch	Body state	None 💌 Max age 30 s
	Route guidance Bathymetry elevation	
	Bathymetry altitude	
8-	Burial	
82	Tension	None 💌
99	Active anchor spread Proposed anchor spread	Vehicles/FPU/Anchors/Anchor Spread
		▼ Vehicles el
		 Anchors Anchor Spread Proposed Anchor Spread

Figure 20 Active Anchor Spread Selection Example



b. **Proposed anchor spread:** This outputs the proposed anchor spread from the selected vehicle containing the anchors

Configure IMCA Telemetry	,	-		$\langle \rangle$
Receive Transmit				
Output Geographic CRS	/GS 84 geographic 2D (4326) _ Selected Report —			
Descriptor	Enabled Transmit Ir	terval (hh:mm:ss) 00:00:01		,
Active Anchors Proposed Anch	Descriptor Body state	Proposed Anchors None Max age 30 s		
	Route guidance			
ų	Bathymetry elevation Bathymetry altitude			
3	Burial			
5,	Tension Active anchor spread	None V		1
9(Proposed anchor spread	Vehicles/FPU/Anchors/Proposed Anch	or Spread	
		None Vehicles	Cancel	
		▼ FPU ▼ Anchors		
		Anchor Spread Proposed Anchor Sprea	ad	

Figure 21 Proposed Anchor Spread Selection Example

2025-06-10T00:06:15.26396122,\$4DANC, Active Anchors,000615.263,1,4, NW1,27.1505536,-91.7257534,2, NE1,27.1689019,-91.7258587,3, SE1,27.1525243,-91.7077492,3, SW1,27.1357946,-91.7267477,3*68
2025-06-10T00:06:16.27108752, \$4DANC, Active Anchors, 000616.270, 1, 4, NW1, 27.1505536, -91.7257534, 2, NE1, 27.1689019, -91.7258587, 3, SE1, 27.1525243, -91.7077492, 3, SW1, 27.1357946, -91.7267477, 3*69
2025-06-10T00:06:17.28524112,\$4DANC, Active Anchors,000617.285,1,4, NW1,27.1505536,-91.7257534,2, NE1,27.1689019,-91.7258587,3, SE1,27.1525243,-91.7077492,3, SW1,27.1357946,-91.7267477,3*62
2025-06-10T00:06:18.29985162, \$4DANC, Active Anchors, 000618.299, 1, 4, NW1, 27.1505536, -91.7257534, 2, NE1, 27.1689019, -91.7258587, 3, SE1, 27.1525243, -91.7077492, 3, SW1, 27.1357946, -91.7267477, 3*60
2025-06-10T00:06:19.30988542, \$4DANC, Active Anchors, 000619.309, 1, 4, NW1, 27.1505536, -91.7257534, 2, NE1, 27.1689019, -91.7258587, 3, SE1, 27.1525243, -91.7077492, 3, SW1, 27.1357946, -91.7267477, 3*69
2025-06-10T00:06:20.3090084Z, \$4DANC, Active Anchors, 000620.308, 1, 4, NW1, 27.1505536, -91.7257534, 2, NE1, 27.1689019, -91.7258587, 3, SE1, 27.1525243, -91.7077492, 3, SW1, 27.1357946, -91.7267477, 3*62
2025-06-10T00:06:21.32238582, \$4DANC, Active Anchors, 000621.322, 1, 4, NW1, 27.1505536, -91.7257534, 2, NE1, 27.1689019, -91.7258587, 3, SE1, 27.1525243, -91.7077492, 3, SW1, 27.1357946, -91.7267477, 3*6B
2025-06-10T00:06:22.32466602, \$4DANC, Active Anchors, 000622.324, 1, 4, NW1, 27.1505536, -91.7257534, 2, NE1, 27.1689019, -91.7258587, 3, SE1, 27.1525243, -91.7077492, 3, SW1, 27.1357946, -91.7267477, 3*6E
2025-06-10T00:06:23.3241434z, \$4DANC, Active Anchors, 000623.323, 1, 4, NW1, 27.1505536, -91.7257534, 2, NE1, 27.1689019, -91.7258587, 3, SE1, 27.1525243, -91.7077492, 3, SW1, 27.1357946, -91.7267477, 3*68
2025-06-10T00:06:24.33761752,\$4DANC,Active Anchors,000624.337,1,4,NW1,27.1505536,-91.7257534,2,NE1,27.1689019,-91.7258587,3,SE1,27.1525243,-91.7077492,3,SW1,27.1357946,-91.7267477,3*6A
2025-06-10T00:06:25.33828612,\$4DANC,Active Anchors,000625.338,1,4,NW1,27.1505536,-91.7257534,2,NE1,27.1689019,-91.7258587,3,SE1,27.1525243,-91.7077492,3,SW1,27.1357946,-91.7267477,3*64

Figure 22 Active Anchor Spread Message Output Example

2025-06-10T00:35:17.7340787Z, \$4DANC, Proposed Anchors, 003517.733, 0, 4, NW1, 27.1524225, -91.7446566, 1, NE1, 27.1689028, -91.7258589, 3, SE1, 27.1525248, -91.7077494, 3, SW1, 27.1359010, -91.7267211, 3*60
2025-06-10T00:35:18.74593572, \$4DANC, Proposed Anchors, 003518.745, 0, 4, NW1, 27.1524225, -91.7446566, 1, NE1, 27.1689028, -91.7258589, 3, SE1, 27.1525248, -91.7077494, 3, SW1, 27.1359010, -91.7267211, 3*6E
2025-06-10T00:35:19.7531307z, \$4DANC, Proposed Anchors, 003519.753, 0, 4, NW1, 27.1524225, -91.7446566, 1, NE1, 27.1689028, -91.7258589, 3, SE1, 27.1525248, -91.7077494, 3, SW1, 27.1359010, -91.7267211, 3*68
2025-06-10T00:35:20.7637292Z, \$4DANC, Proposed Anchors, 003520.763, 0, 4, NW1, 27.1524225, -91.7446566, 1, NE1, 27.1689028, -91.7258589, 3, SE1, 27.1525248, -91.7077494, 3, SW1, 27.1359010, -91.7267211, 3*61
2025-06-10T00:35:21.79170402, \$4DANC, Proposed Anchors, 003521.791,0,4, NW1,27.1524225, -91.7446566,1, NE1,27.1689028, -91.7258589,3, SE1,27.1525248, -91.7077494,3, SW1,27.1359010, -91.7267211, 3*6D
2025-06-10T00:35:22.80207482, \$4DANC, Proposed Anchors, 003522.801, 0, 4, NW1, 27.1524225, -91.7446566, 1, NE1, 27.1689028, -91.7258589, 3, SE1, 27.1525248, -91.7077494, 3, SW1, 27.1359010, -91.7267211, 3*68
2025-06-10T00:35:23.81098922, \$4DANC, Proposed Anchors, 003523.810,0,4, NW1, 27.1524225, -91.7446566, 1, NE1, 27.1689028, -91.7258589, 3, SE1, 27.1525248, -91.7077494, 3, SW1, 27.1359010, -91.7267211, 3*69
2025-06-10T00:35:24.81692932, \$4DANC, Proposed Anchors, 003524.816,0,4,NW1,27.1524225,-91.7446566,1,NE1,27.1689028,-91.7258589,3,SE1,27.1525248,-91.7077494,3,SW1,27.1359010,-91.7267211,3*68
2025-06-10T00:35:25.83131912, \$4DANC, Proposed Anchors, 003525.831,0,4, NW1, 27.1524225, -91.7446566, 1, NE1, 27.1689028, -91.7258589, 3, SE1, 27.1525248, -91.7077494, 3, SW1, 27.1359010, -91.7267211, 3*6C
2025-06-10T00:35:26.84345692, \$4DANC, Proposed Anchors, 003526.843,0,4, NW1, 27.1524225, -91.7446566,1, NE1, 27.1689028, -91.7258589, 3, SE1, 27.1525248, -91.7077494, 3, SW1, 27.1359010, -91.7267211, 3*6A
2025-06-10T00:35:27.85494882, \$4DANC, Proposed Anchors, 003527.854,0,4, NW1, 27.1524225, -91.7446566,1, NE1, 27.1689028, -91.7258589, 3, SE1, 27.1525248, -91.7077494, 3, SW1, 27.1359010, -91.7267211, 3*6D
2025-06-10T00:35:28.85934942, \$4DANC, Proposed Anchors,003528.859,0,4, NW1, 27.1524225, -91.7446566, 1, NE1, 27.1689028, -91.7258589, 3, SE1, 27.1525248, -91.7077494, 3, SW1, 27.1359010, -91.7267211, 3*6F
2025-06-10T00:35:29.86832792, \$4DANC, Proposed Anchors,003529.867,0,4,NW1,27.1524225,-91.7446566,1,NE1,27.1689028,-91.7258589,3,SE1,27.1525248,-91.7077494,3,SW1,27.1359010,-91.7267211,3*63
2025-06-10T00:35:30.87050202, \$4DANC, Proposed Anchors, 003530.870,0,4, NW1, 27.1524225, -91.7446566, 1, NE1, 27.1689028, -91.7258589, 3, SE1, 27.1525248, -91.7077494, 3, SW1, 27.1359010, -91.7267211, 3*6D
2025-06-10T00:35:31.8761277Z,\$4DANC, Proposed Anchors,003531.875,0,4,NW1,27.1524225,-91.7446566,1,NE1,27.1689028,-91.7258589,3,SE1,27.1525248,-91.7077494,3,SW1,27.1359010,-91.7267211,3*69

Figure 23 Proposed Anchor Spread Message Output Example